An advanced CFD postprocessing tool enabled by adjoint and RBF mesh morphing allows the fast exploration of an arbitrary number of shape parameters effect on performances

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AT THE EPICENTRE OF THE DIGITAL TRANSFORMATION OF INDUSTRY

36th INTERNATIONAL CAE CONFERENCE AND EXHIBITION

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Outline

- RBF Morph technology and software solutions for shape optimization
- Gradient based examples based on adjoint solver
- Beyond (before) optimization: advanced **post processing**
- Industrial example: exploring the drag reduction of a Formula Indy car
- Conclusions



10+ years of RBF Morph



Industries served (100+ institutions)



Automotive



Aerospace & Defence



Healthcare & Medical



Nautical & Marine



Energy



Radial Basis Functions mesh Morphing

- We offer Radial Basis Functions (RBF) to drive mesh morphing (smoothing) from a list of source points and their displacements
 - Surface shape changes
 - Volume mesh smoothing
- RBF are recognized to be one of the best mathematical tool for mesh morphing

$$\begin{cases} s_{x}(\boldsymbol{x}) = \sum_{i=1}^{N} \gamma_{i}^{x} \varphi(\|\boldsymbol{x} - \boldsymbol{x}_{s_{i}}\|) + \beta_{1}^{x} + \beta_{2}^{x} \boldsymbol{x} + \beta_{3}^{x} \boldsymbol{y} + \beta_{4}^{x} \boldsymbol{z} \\ s_{y}(\boldsymbol{x}) = \sum_{i=1}^{N} \gamma_{i}^{y} \varphi(\|\boldsymbol{x} - \boldsymbol{x}_{s_{i}}\|) + \beta_{1}^{y} + \beta_{2}^{y} \boldsymbol{x} + \beta_{3}^{y} \boldsymbol{y} + \beta_{4}^{y} \boldsymbol{z} \\ s_{z}(\boldsymbol{x}) = \sum_{i=1}^{N} \gamma_{i}^{z} \varphi(\|\boldsymbol{x} - \boldsymbol{x}_{s_{i}}\|) + \beta_{1}^{z} + \beta_{2}^{z} \boldsymbol{x} + \beta_{3}^{z} \boldsymbol{y} + \beta_{4}^{z} \boldsymbol{z} \end{cases}$$

Biancolini, M. E. (2017). *Fast radial basis functions for engineering applications*. Springer International Publishing.

Parametric CAE models

CAE models supported includes flow analysis (CFD) and structural analysis (FEM)

RBF Morph makes the CAE model parametric with respect to the shape.

Works for any size of the mesh.

Shape parameters can be steered with the optimizer of choice.





- It's easy and fast: shape parameters are defined in the CAE GUI. No need to iterate the CAD
- The turnaround time of the optimization is usually reduced by a factor five (weeks become days)

We offer Ansys integrated solutions...

ACT Extension (FEM)

- Released in 2014
- Fully embedded in ANŚYS Mechanical (parametric)
- Benefits of underlying geometry (or aux geo with dead meshes) ...WB Meshing



Fast RBF mesh morphing technology that makes the mesh shape parametric with a few clicks. Basic and hierarchical shape modifications defined in the tree. Automatic shape optimisation now included.

Meshing



Fluent Module (CFD)

- Released in 2009
- Fully integrated within Fluent (GUI, **TUI & solving** stage), Workbench and **Adjoint** Solver
- Multi physics features (FSI)

...and a Stand Alone software



Released in 2011

- Read in STL and CGNS file formats
- Solver independent process that supports many mesh formats
- Scriptable via tcl

RBF Morph Fluent Module





Fluent module

- Add on fully integrated within Fluent (GUI, TUI & solving stage), Workbench and Adjoint Solver
- Mesh-independent RBF fit used for surface mesh morphing and volume mesh smoothing
- Parallel calculation allows to morph large size models (many millions of cells) in a short time
- Management of every kind of mesh element type (tetrahedral, hexahedral, polyhedral, etc.)
- Support of the CAD re-design of the morphed surfaces
- Multi fit makes the Fluent case truly parametric (only 1 mesh is stored)
- Precision: exact nodal movement and exact feature preservation (RBF are better than FFD)



Gradient-based optimization (adjoint)



Optimization with parameters

The adjoint formulation provides the gradient of an aerodynamic objective function with respect to surface displacements

$$\frac{\delta F}{\delta \vec{b}} = \frac{\delta F}{\delta x_{\kappa}} \frac{\delta x_{\kappa}}{\delta \vec{b}}$$

 RBF Morph provides the deformation velocity (adjoint preview)

5

47

45

43

37

35

33

0

Engine Air box

7.94e+01 6.93e+01 5.93e+01 4.92e+01

-1.13e+01

-2.13e+01

10

3.91e+01 2.90e+01 1 90e+01 8 89e+00 -1.19e+00

20

15

Optimization cycles

25

30

	Ma

	Mean pressure Drop [Pa]	Unbalance
Baseline	39.7	12.45%
Optimized	33.635	0.12%
Reduction	15.3%	99.0%



- 32 shape parameters are used to control the geometry of the plenum and of the three runners
- Obtained shape allows to get a 15.3% reduction of pressure drop and uniform distribution

Engine Air box





- V12 700Hp@8250RPM
- Obtained shape allows to get a 5.9% reduction of pressure drop

Beyond (before) optimization: advanced adjoint based post-processing

- High fidelity CAE solver adopted in this study is Ansys Fluent (CFD+adjoint)
- Advanced mesh morphing is provided by combining the CFD solver with the RBF Morph Fluent module
- A new interactive custom feature defined to quickly explore new shapes without any additional solver calculations



Beyond (before) optimization: advanced adjoint based post-processing



- 1. Inspect flow solution and adjoint sensitivity
- 2. Decide the regions to be modified
- 3. Create desired shape modifications (design parameters, FEA deflections, sculpted shapes)
- 4. Explore how shape modifications combines and get a (gradient based) estimation of the performance

- Half car model comprised of about 80 millions cells
- Drag sensitivity computed with adjoint solver
- Regions of interest:
 - Windshield
 - Rear wheel deflector



- Shape modifications are defined to get a variety of feasible new shapes
 - Windshield is controlled by 9 different actions
 - Rear wheel deflector is controlled by 3 different actions



- Shape modifications are defined by filtering adjoint sensitivity field that allows to get a new optimal shape for
 - Windshield
 - Rear wheel deflector







all

Console

Morph preview on 2 ID(s), with θ total points...
Morph preview on 2 ID(s), with θ total points...
Objective function variation: θ
Corresponding to a drag improvement equal to θ drag counts

mesh/

plot/

report/

server/

parallel/

>

adjoint/ define/ display/ exit file/ solve/ surface/ views/

1

The challenge

- Well, now we have a quantitative estimation of the effect of shape parameters
- Automatic methods are based on the gradient and can converge toward an optimum
- Can the engineer get a better shape in a single shot?

...to answer...

- Sensitivities are valid only around the baseline
- Too much variation could be risky
- A small variation is safer... but predicts a small gain!
- (challenge posed on Friday to get the answer after the week end)

Predicted result

- The new shape was defined combining the 3 parameters (2 on the windshield, 1 on the rear wheel deflector) that show most promising results
- A 0.5% reduction of the drag force has been predicted
- The new model has been generated and submitted for a full CFD run



Console

608409 polygons displayed.

Objective function variation: 0

Corresponding to a drag improvement equal to 0 drag points

mesh/	solve/
parallel/	surface/
plot/	views/
report/	
server/	
	mesh/ parallel/ plot/ report/ server/

> (rbf-adjoint-interactive '((sidepod_5 -0.3)(cupolino_cyl_1 0.2)(cupolino_cyl_2 -0.2)))

Predicted result

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Console

AUJUINE EVALUATION = "1.31/31

Morphing-Adjoint evaluation done in 0 sec.

Sequential Morph Adjoint done in 0 sec. /display/surface-grid (48 51 55 56 54 52 53 59 57 58 60 47 63 31 30 41 40 43 21 22 23 44 17 45 16 18 15 20 36 34 35 19 39 37 38

> MaxDisp = 0.015002 MaxSkew = 6.329179e-01 608409 polygons displayed.

Objective function variation: -7.9179111 Corresponding to a drag improvement equal to -0.25854403 drag points

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Obtained result

- A 1% reduction of the drag force has been obtained!
- A 0.49 drag points reduction (0.5392 → 0.5343) achieved
- The breakdown of drag
 distribution has been inspected

zone w01aa-bw-cha w01aa-bw-driv w01aa-bw-eng	Cd baselin ssis 0.0503955 er -0.0288661 ine-cover 0.0051390	neCd modified0.0495229770.027914999050.005075394	difference -0.0008726 0.00095112 -6.366E-05			
w01aa-bw-side w01ab-mech-e w01ab-mech-e w01ab-mech-ra	τ Ζ (one	Cd I	paseline	Cd modified	difference
w01ab-mech-r w01ab-mech-r w01ba-fuw-ski w01ba-fuw-ste w01bb-ruw-dif w01bb-ruw-ski	w01aa-bw-	chassis	0.05	0395574	0.049522977	-0.0008726
w01bb-ruw-top w01bb-ruw-tyr w02-fw-endpla w02-fw-main w03-rw-endpla	w01aa-bw-	driver	0.02	8866122	-0.027914999	0.00095112
w03-rw-endpia w03-rw-pylon w04-fs-inf w04-fs-pull w04-fs-sup w04-fs-track	w01aa-bw-	engine-cov	ver 0.00	-	0.005075394	-6.366E-05
w05-rs-drivesh w05-rs-inf w05-rs-push w05-rs-sup	์w01aa-bw-	sidepod	0.00	1937374	-0.006622437	-0.0046851
w05-rs-track w06a-fwls-plat w06b-fwlr-rim w06b-fwlr-tyre	• -		0.03	6997341	0.038567107	0.00156977
w06b-fwlr-tyre w07a-rwls-plat w07b-rwlr-rim w07b-rwlr-tyre w07b-rwlr-tyre	'w07b-rwlr-	tyre-rear	0.14	1861484	0.14882451	0.00020967
total	total		0.5	391928	0.53432232	-0.0048705

Original shape (Cd= 0.5392)

Optimized shape (Cd= 0.5343)



Original shape (Cd= 0.5392)



Optimized shape (Cd= 0.5343)



Original shape (Cd= 0.5392)

Optimized shape (Cd= 0.5343)

Original shape (Cd= 0.5392)

Optimized shape (Cd= 0.5343)

Conclusions

- There is a need for advanced tools to get as more information as possible from high fidelity CFD
- When shape sensitivities are available (adjoint solution) we can compute derivatives of performance vs. parameters
- In this study we presented (rbf-adjoint-interactive) a new tool based on Ansys Fluent, and RBF Morph that allows to predict the effect of shape on performance without the need of a new CFD computation
- The proposed method was applied to reduce the aerodynamic drag of a Dallara Indy Car acting on the windshield and on the rear wheel deflector gaining a 0.49 drag points

Thank you!

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